2.4 Paths and curves

We all know what curves are. Often we can describe them in more than one way:

c(t) = (cost, sint)

X

- as points satisfying an equation, like $y = x^2$
- parametrically, like $c(t) = (t, t^2)$

This section is about the parametric description. It provides a different way to describe functions $c : R \rightarrow R^n$, and also a way to understand the curves.

Terminology: a path is a mapping $c : [a,b] \rightarrow R^n$

The velocity vector of a path c(t).

If $c(t) = (c_1(t), \dots, c_n(t))$ are the component functions, the velocity of c is $c'(t) = (c_1'(t), \dots, c_n'(t))$

It's length is the speed. It points in the tangent direction to the curve at c(t).

Typical question: Consider the path c(t) = t(cos(t), sin(t)) a. Find the velocity vector of c at t=2

$$c'(t) = (cost - tsint, sint + tcost)$$

b. Find the equation of the tangent line to the curve at c(2).

$$v = c(2) + 5 c'(2)$$